Why machine learning? Introduction to ML and Regression Majority of the modern combased on machine learning Statistical Natural Language Processing Tokenization
 Part of speech tagging Cağrı Cöltekin Parsing Speech recognition
 Named Entity recognitic
 Document classification
 Question answering
 Machine translation University of Tübingen Seminar für Sprachwissenschaft Summer Semester 2021 Machine learning is ... The field of machine learning is concerned with the question of how to construct computer programs that automatically improve with experience. —Mitchell (1997) Machine Learning is the study of data-driven methods capable of mi understanding and aiding human and biological information processing to —Barber (2012) Statistical learning refers to a vast set of tools for understanding data.

—James et al. (2013)

Supervised or unsupervised

\* Machine learning methods are often divided into two broad categories supervised and unsupervised · Supervised methods rely on labeled (or annotated) data

. Unsupervised methods try to find regularities in the data without any (direct) supervision . Some methods do not fit any (or fit both):

 Semi-supervised methods use a mixture of both
 Reinforcement learning refers to the methods wh
delayed In this course, we will mostly discuss/use supervised methods

Unsupervised learning

 In unsupervised learning we do not ha any labels The aim is discovering some 'latent'

structure in the data Common examples include

- Clustering - Density est \* The methods that do not require (ma annotation are sometimes called

al linguistic tasks and applications are

unsupervised

Supervised learning

Supervised learning

A supervised ML method is called regression if the outcome to be predicted is a numeric (continuous) variable classification if the outcome to be predicted is a categorical variable

Regression

Classification

2

+ (Linear) Regression (today) \* Classification (perceptron, logistic regression, ANNs)

· Evaluating ML methods / algorithms Unsupervised learning

ML topics we will cover in this course

Sequence learning

Machine learning and statistics

- The methods largely overlap (it was even suggested that both should be collectively called 'data science')
- Aims differ - In statistics (used as in experimental sciences) aim is making infi
- the models

  In machine learning correct predictions are at the focus

A more diverse set of models/methods are used in ML

### Machine learning and models

- \* A machine learning method makes its predictions based on a model
- The models are often parametrized: a set of parameters defines a model
- Learning can be viewed as finding the 'best' model among a family of models (that differ based on their parameters)

### The linear equation: the regression model



# Notation differences for the regression equation

- $y_t = wx_t$ + Sometimes, Greek letters  $\alpha$  and  $\beta$  are used for intercept and the slope respectively
- \* Another common notation to use only b,  $\beta, \theta$  or w, but use subscripts,  $\theta$
- indicating the intercept and 1 indicating the slope . In machine learning it is common to use w for all coefficients (sometimes you
- \* Sometimes coefficients wear hats, to emphasize that they are estimates . Often, we use the vector notation for both input(s) and coefficients:
- $\mathbf{w} = (\mathbf{w}_0, \mathbf{w}_1)$  and  $\mathbf{x}_1 = (1, \mathbf{x}_1)$

### Parameter estimation

- Learning is selecting a model from a family of models that differ in their parameters . In ML, we are interested in finding the best model based on data
- Typically, we seek the parameters that reduce the prediction error on a
- training set
- Ultimately, we seek models that do not only do well on the training data, but

# Estimating regression parameters

- · We view learning as a search for the
- regression equation with least erro The error terms are also called
- We want error to be low for the whole training set: average (or sum)
- of the error has to be reduced . Can we minimize the sum of the



# Short digression: minimizing functions

In least squares regression, we want to find  $w_0$  and  $w_1$  values that mini

$$E(\mathbf{w}) = \sum_{i} (y_i - (w_0 + w_1x_i))^2$$

- Note that  $E(\mathbf{w})$  is a quadratic function of  $\mathbf{w} = (w_0, w_1)$
- As a result, E(w) is convex and have a single extreme val
   there is a unique solution for our minimization problem
- ${\boldsymbol *}$  In case of least squares regression, there is an analytic solution

- Even if we do not have an analytic solution, if the error function is con search procedure like gradient descent can still find the global minimum

# Regression with multiple predictors

$$y_1 = \underbrace{w_0 + w_1 x_{i,1} + w_2 x_{i,2} + \ldots + w_k x_{i,k}}_{t} + \varepsilon_1 = w x_1 + \varepsilon_1$$

- $w_0$  is the intercept (as before)
- $w_{1..k}$  are the coefficients of the respective predictors
  - + using the vector notation the equation becomes
  - $\varepsilon_{\phantom{0}}$  is the error term (residual)

where  $\mathbf{w} = (w_0, w_1, \dots, w_k)$  and  $\mathbf{x}_k = (1, x_{i,1}, \dots, x_{i,k})$  $(\dots, w_1, \dots, w_k)$  and  $x_i = (1, x_{i,1}, \dots, x_{i,k})$ It is a generalization of simple regression with some additional power and complexity. The simple linear model

# $y_1 = a + bx_1$

- mre (or response, or dependent) variable. The index i repr each unit observation/measurement (sometimes called a 'case') x is the predictor (or explanatory, or independent) variable
- a is the intercept (called bias in the NN literature)
- b is the slope of the regression line. a and b are called coefficients or parameters
- a + bx is the model's prediction of  $\psi(\hat{\psi})$ , given x

# Regression models with multiple predictors

- The equation defines a (hyper)plane
- · With 2 predictors  $y = w_0 + w_1x_1 + w_2x_2$
- convenient to use the vector







# Least-squares regression

 Find w<sub>0</sub> and w<sub>1</sub>, that minimize the sum of the squared errors (SSE)  $\mathbb{E}(\mathbf{w}) = \sum c_1^2 = \sum (\mathbf{y}_1 - \hat{\mathbf{y}}_1)^2 = \sum (\mathbf{y}_1 - (\mathbf{w}_0 + \mathbf{w}_1 \mathbf{x}_1))^2$ 

$$w_1 = \frac{\sigma_{xy}}{\sigma_x^2} = r \frac{s d_y}{s d_x} \qquad \qquad w_0 = \bar{y} - w_1 \bar{x}$$

What is special about least-squares? \* Minimizing MSE (or  $SS_R)$  is equivalent to MLE estimate under the assumption  $c \sim \mathcal{N}(0,\sigma^2)$ 

· Working with 'minus log likelihood' is more cor

$$E(w) = -\log \mathcal{L}(w) = -\log \prod_{i} \frac{e^{-\frac{(w_i - \psi_i)^2}{2\sigma^2}}}{\sigma \sqrt{2\pi}}$$

$$L(w) = -\log 2(w) = -\log \frac{1}{4} \frac{1}{\sigma \sqrt{2\pi}}$$

$$\dot{w} = \underset{w}{\operatorname{arg\,min}} (-\log \mathcal{L}(w)) = \underset{w}{\operatorname{arg\,min}} \sum_{i} (y_i - \dot{y}_i)^2$$
  
other error functions, e.g., absolute value of the errors, that can be

# Evaluating machine learning systems

- . Any (machine learning) system needs a way to measure its success For measuring success (or failure) in a machine learning system we need quantitative measures
- Remember that we need to measure the success outside the training data

### Measuring success in Regression

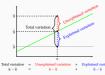
· Root-mean-square error (RMSE)

$$RMSE = \sqrt{\frac{1}{n}\sum_{i}^{n}(y_{i} - \hat{y}_{i})^{2}}$$

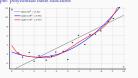
Another well-known measure is the coefficient of determination

 $R^2 = \frac{\sum_{i}^{n}(\hat{y}_i - \hat{y})^2}{\sum_{i}^{n}(y_i - \hat{y})^2} = 1 - \left(\frac{RMSE}{\sigma_u}\right)$ 

## Explained variation



### Example: polynomial basis functions



Overfitting

# Regularized parameter estimation

- \* Regularization is a general method for avoiding overfitting The idea is to constrain the parameter values in addition to minimizing the
  - training error For example, the regression estimation be

$$\hat{\mathbf{w}} = \operatorname*{arg\,min}_{w} \sum_{t} (y_{t} - \hat{y}_{t})^{2} + \lambda \sum_{j=1}^{k} w_{j}^{2}$$

- + The new part is called the regularization term
- \*  $\lambda$  is a hyperparameter that determines the strength of the regularization
- . In effect, we are preferring small values for the coefficients
- . Note that we do not include w., in the regularization term

L1 regularization

In L1 regularization we mis

$$E(w) + \lambda \sum_{j=1}^{k} |w_j|$$

- + The additional term is the L1-norm of the weight vector (excluding  $w_{\text{\tiny D}})$
- In statistics literature the L1-regularized regression is called lasso
- . The main difference from L2 regularization is that L1 regularization forces some values to be 0 - the resulting model is said to be 'sparse'

\*  $100 \times R^2$  is interpreted as 'the percentage of variance explained by the model' R<sup>2</sup> shows how well the model fits to the data: closer the data points to the regression line, higher the value of R<sup>2</sup>

 $\frac{\text{Explained variation}}{\text{Total variation}} = \frac{\sum_{i}^{n} (\hat{y}_{i} - \hat{y})^{2}}{\sum_{i}^{n} (y_{i} - \hat{y})^{2}}$ 

In simple regression, it is the square of the correlation coefficient between the

We can express the variation explained by a regression model as

### Dealing with non-linearity

outcome and the predictor

. The range of R2 is [0, 1]

Assessing the model fit: R2

- Least-squares estimation works because the regression equation is linear with respect to parameters w (error function is quadratic)
- Introducing non-linear combinations of inputs does not affect the estimation procedure. The following are still linear models
  - $y=w_0+w_1x^2+\varepsilon$  $y = w_0 + w_1 \log(x) + \epsilon$
- $y=w_0+w_1x_1+w_2x_2+w_3x_1x_2+\varepsilon$ \* In general, we can replace input x by a function of the input(s)  $\Phi(x).$   $\Phi()$  is
- called a hosis function Basis functions allow linear models to model non-linear relations by
- transforming the input variables

# Overfitting

- Overfitting is an important problem in ML, happens when the n peculiarities/noise in the training data
  - . An overfitted model will perform well on training data, but worse on
  - new/unseen data · Typically 'more complex' models are more likely to overfit

### Preventing overfitting

- A straightforward approach is to chose a simpler model (family), e.g., by reducing the number of predictors
- . More training data helps: it is less likely to overfit if number of training
  - instances are (much) larger than the paramters
- There are other methods (one is coming on the next slide)
- . We will return to this topic frequently during later lectures

L2 regularization

The form of regularization, where we minimize the regularized cost function  $E(\mathbf{w}) + \lambda ||\mathbf{w}||_2$ 

### is called L2 regularization.

- \* Note that we are minimizing the L2-norm of the weight vector
- In statistic literature L2-regularized regression is called ridge regre-
- . The method is general: it can be applied to other ML methods as well The choice of λ is important
- - . Note that the scale of the input also becomes important

# Regularization as constrained optimization

I.1 and I.2 regularization can be viewed as minimization with constraints L2 regularization

Minimize E(w) with constraint ||w|| < s

L1 regularizati

Minimize E(w) with constraint  $||w||_1 < s$ 

· Regularization prevents overfitting The hyperparameter λ needs to be determ

Regularization: some remarks

best value is found typically using a grid search, or a random sear
 it is tuned on an additional partition of the data, development set
 development set cannot overlap with training or tost set

\* The regularization terms can be interpreted as priors in a Bayesian setting

\* Particularly, L2 regularization is equivalent to a normal prior with zero n

# Gradient descent for parameter estimation

- . In many ML problems, we do not have a closed form solution for finding the minimum of the error function . In these cases, we use a search strategy
- Gradient descent is a search method for finding a minimum of a (error)
- . The general idea is to approach a minimum of the error function in small steps  $\mathbf{w} \leftarrow \mathbf{w} - \eta \nabla J(\mathbf{w})$

 $\nabla J$  is the gradient of the loss function, it points to the direction of the maxim increase  $\eta$  is the learning rate

# Gradient descent with single parameter

- · For a single para eter, gradient is a one-dimensional vector
- The direction of gradient is tow the maximum inc
- We take steps proportional to
- . Steeper the curve, the larger the parameter update



# Gradient descent with single parameter





### Categorical predictors

- Categorical predictors are represented as multiple binary coded input variables
- . For a binary predictor, we use a single binary input. For example, (1 for one of the values, and 0 for the other)

$$x = \begin{cases} 0 & \text{for male} \\ 1 & \text{for female} \end{cases}$$

- For a categorical predictor with k values, we use one-hot encoding (other coding schemes are possible)
  - $x = \begin{cases} (0,0,1) & \text{neutral} \\ (0,1,0) & \text{negative} \end{cases}$ (1,0,0) positive

### Summary

# What to remember

### Supervised vs. unsupervised learners

- MSE, R<sup>2</sup> · Regression vs. classification non-linearity & basis function
- · Linear regression equation \* L1 & L2 regularization (lasso and
- . Least-square estimate

### Next: Wed classification

- Fri first lab session
- Mon classification

B

### Additional reading, references, credits \* Hastie, Tibshirani, and Friedman (2009) discuss introductory bits in chapter

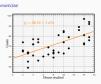
- 1, and regression on chapter 3 (sections 3.2 and 3.4 are most relevant to this lecture) Jurafsky and Martin (2009) has a short section (6.6.1) on regression
- You can also consult any machine learning book (including the ones listed) below)

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## A hands-on exercise



A hands-on exercis



# A hands-on exercise



### A hands-on exercise

